Researches on the Multi-ontology based Avionics Electronics Systems Software Requirements Elicitation Approach

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Abstract

Nowadays, there are many researches on the ontology-based requirements elicitation approach. However, there are still some disadvantages. One is lacking of researches on aviation electronics (AE) systems ontology. The other is the existing ontologybased requirements elicitation approaches do not involve dynamic ontology knowledge and requirements error knowledge. This paper adopts ontology to construct the requirements knowledge multi-ontology framework (RKMOF) of AE system. Moreover it introduces the software requirements error pattern (SREP) which is merged into the RKMOF to enrich ontology knowledge. Furthermore the ontology-based requirements elicitation approach can be obtained according to the above framework. The SREP can be weaved into the task ontology by aspect-oriented method (AOM). Finally, a case study is presented to validate the effectiveness of the proposed requirements elicitation approach. The results show that the number of errors in requirements specification (RS) obtained by the proposed approach is less than the comparative approach. It shows that the proposed approach is effective.

1 Introduction

Requirements elicitation not only affects the requirements quality directly, but affects the software reliability greatly. Domain knowledge plays an important role in eliciting high quality requirements [1]. An ontology is an explicit specification of а conceptualization [3]. Therefore it is effective to introduce ontology method to requirements elicitation to improve the completeness of knowledge. Nowadays, the typical representatives of ontology-based requirements elicitation approach include, the requirements elicitation approach based on the multi-ontology framework [2], the automatic requirements elicitation approach based on enterprise ontology [4, 5], the approach of using domain ontology as domain knowledge for requirements elicitation [1] and the requirements elicitation and analysis approach based on formal expression of primitive requirements through top-down refinement of the meta-model [6]. The first two approaches mainly solved the ambiguity and inconsistency problems in requirements elicitation. However, the second one contained static knowledge only. The third approach primarily studied the ontology-based requirements elicitation and analysis and the quality measurement of RS. Thus it did not study how to construct high quality ontology deeply. The fourth approach mainly studied how estimate completeness and consistency to of requirements. However, it did not guide requirements elicitation. Besides the above problems, there are still some common issues, i.e., how to construct AE systems ontology and how to construct ontology with considering the requirements error knowledge. However, it is considerable to study the above two issues.

For the purpose of solving the above issues, this paper introduces a new requirements elicitation approach based on the AE systems RKMOF with the SREP. The rest of this paper is organized as follows. In section 2, this paper presents the AE systems RKMOF based on knowledge aided design system (KADS). In section 3, it introduces the AE systems requirements knowledge ontology structure in detail. Section 4 presents the definition and representation of the SREP. Section 5 proposes the process of requirements elicitation method based on the RKMOF with the SREP. In section 6, an instance of unmanned aerial vehicle (UAV) flying control (FC) system is shown to validate the effectiveness of the proposed approach. Section 7 is the conclusion.

2 The AE systems RKMOF

KADS is adopted to construct knowledge systems frequently. However, it has some deficiencies, e.g., lacking strong ties between different knowledge layers, incompleteness of knowledge, etc. Ontology is an effective way to integrate independent knowledge layers to form an integrated knowledge system. The definition of the AE systems RKMOF is,

Definition1 RKMOF = $\langle AEGO, DO, TO, AO \rangle$, where AEGO, DO, TO, AO represents the AE systems generalized ontology, domain ontology, task ontology and application ontology respectively.

The relationships between various ontologies are shown in Fig.1. The AEGO can be mapped onto the TO and instantiated to the DO. Moreover, the DO can be instantiated to the AO. Both DO and TO can be reused in the same area, translated into the domain requirements model (DRM) by domain analysis and the application requirements model (ARM) by reuse. Documents, domain knowledge, error data and industry standards are all sources of the DO. DO is divided into the action ontology (ACO), process ontology (PO) and structure ontology (SO). This framework is multi-viewpoint because stakeholders all participate in the framework construction.

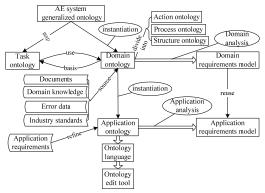


Fig. 1 The AE systems RKMOF

3 The structure of AE systems requirements knowledge ontology

3.1 The construction elements of AE systems requirements knowledge ontology

The universal set of ontology construction elements is, *Element Set* = {*Concepts, Object-property, Dataproperty, P^R, P^C, Inherit-hierarchies, Relations, Instances, Map, Rules*}. *Concepts* refers to system component, function, behavior, etc. *Inherit-hierarchies* is regarded as a special case of *Relations. Object-property* which is a bridge for associating different instances and *Data-property* which is a bridge for associating an instance and a value are two types of property. *P^R* represents property restraints of property value type, range, etc. *P^C* represents property characteristics, e.g., property "interact" of "system" is symmetric. *Map* represents mapping between ontologies in different hierarchies. *Rules* includes axioms and user-defined rules.

3.2 The AE systems requirements knowledge ontology hierarchic structure

Ontologies in various hierarchies can be constructed by using different construction elements introduced above. We will introduce the ontology structure in detail.

3.2.1 The structure of AEGO

The definition of AEGO is,

Definition2 $AEGO = \langle Concepts, Object-property, P^C, Inherit-hierarchies, Relations>.$

It shows that the AEGO can be constructed by constructing its concept (class), class hierarchy, relation, property and property characteristic.

In Fig.2, the concept classes marked with "*" are nonterminals, while the rest of them are terminals. There is an inheritance between child class and its father class. Fig.2 also shows that AEGO concepts not only include static elements, but include dynamic elements.



Fig. 2 A part of hierarchies of concept classes in AEGO

According to above AEGO structure, this paper acquires a part of the AEGO concept relation as Tab.1. The left of arrow is source concept node while the right is destination concept node.

| Ta | b. 1 A p | art of concept rel | ation definition | on |
|----|----------|--------------------|--------------------------------|----|
| | Type↩ | Relation ¢ | P roperty¢ ² | |
| | Sub-aim@ | aim→aim₽ | partial ordering# | |
| | Need* | task→resource+ | support ⁻¹ * | |
| | Sunnorte | resource-+task+ | need-1+ | |

 Interacte²
 system..tenvironmente²
 symmetry²

 Notes: "Need" and "need⁻¹" are mutually inverse.

"Support" and "support⁻¹" are mutually inverse.

Fig.3 shows a part of the AEGO concept space consisting of concepts and relations.

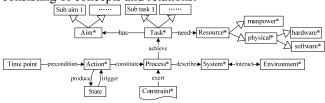


Fig. 3 A part of the AEGO concept space

3.2.2 The structure of DO

The DO is a special ontology for describing designated domain knowledge which includes domain

concepts, relations, activities and criterions. It can be obtained by instantiation of the AEGO.

Definition4 $DO = \langle DomConcepts, Object-property, Data-property, <math>P^{R}$, P^{C} , DomInherit-hierarchies, DomRelations, Rules, Dommap>.

DomInherit-hierarchies is a domain concept inheritance relations set. The relation of inheritance is a dualistic relation involving two parameters which can be depicted by "cardinality" and "status". DomInherithierarchies = < DomInherit-ID, Argument < Argument1 <cardinality, (status)>, Argument2< cardinality, (status)>>>, (Argument1, Argument2 \in DomConcepts).

DomRelations is a set of domain concept relations except *DomInherit-hierarchies*. *Dommap* is a total function mapping from *DomConcepts* to *Concepts*. Thus, equivalent relation " \equiv_{domain} " can be defined as,

Definition5 $a \equiv_{domain} b$ iff Dommap (a) = Dommap (b) = t, a, $b \in DomConcepts$, $t \in Concepts$.

This paper gives an instance of the structure of FC systems DO. A part of FC systems domain concept set is shown in Tab.2 and a part of FC systems concept relation set is shown in Tab.3.

| Tab. 2 A | part of domain | concept set of FC | systems DO |
|----------|----------------|-------------------|------------|
|----------|----------------|-------------------|------------|

| Domain concept name# | Corresponding "Concepts" |
|------------------------------|--------------------------|
| FC-system-software↔ | system₽ |
| Flying control* | aim₽ |
| Attitude/direction control | task≠ |
| Response time# | constraint₽ |
| Switchover of CPU redundancy | action+ ² |

Tab. 3 A part of concept relation set of FC systems DO

| Type₽ | Source node≠ | Aimnode₽ |
|---------------------|------------------------------|-------------------------|
| Has-aim¢ | attitude/direction control+? | flying control+ |
| Has-aim¢ | navigation computing | flying management \wp |
| Direct-interact+? | FC system₽ | power-system₽ |
| Direct-interact+? | FC system₽ | task equipment₽ |
| Indirect-interact+3 | FC system+ | geography environment+ |

3.2.3 The structure of AO

This paper collects application requirements concepts and relations based on the AEGO and DO according to the purpose of AE systems requirements.

Definition6 $AO = \langle AppConcepts, Object-property, Data$ $property, <math>P^{R}$, P^{C} , AppInherit-hierarchies, AppRelations, Appmap, Rules \rangle .

Definition7 $a \equiv_{app} b$ iff Appmap (a) = Appmap (b) = t, a, $b \in AppConcepts$, $t \in Concepts$.

The explanations for the definition 6 and 7 are omitted because they are similar to the definition 4 and 5.

3.2.4 The structure of TO

The TO supplies primitives for context description and makes process of merging domain knowledge into the context more convenient. The definition of requirements elicitation task ontology (RETO) is presented as follows.

Definition8 RETO: = <Requirement-Eliciting Task, Requirement-Eliciting Task-PSM, Requirement-Eliciting Taskmap>, where Requirement-Eliciting Task: = < Task ID, Circumstance >, Requirement-Eliciting Task-PSM: = < Competence, Operational specification, Requirements >, Competence: = < Input Behavior, Output Behavior, Goal >, Operational specification: = < Inference Steps, Control Flow between the Inference Steps, Data Flow between the Inference Steps >, Requirements: = < Concepts, Relations, Facts, Rules >, Requirement-Eliciting Taskmap:{ Requirement-Eliciting Task Concepts > Concepts}

Due to the limited space, we do not introduce the details of the RETO in this section. It will be introduced in the section 5 with a concrete instance.

4 The definition and representation of SREP

Requirements error is the summary of errors in software requirements engineering (SRE). The definition of SREP is introduced as follows referring to the definition of software error pattern [7].

Definition9 SREP is the specific error which arises in all stages of SRE, occurs repeatedly in a certain direct scenario, propagates emanative in design and coding stages and may cause system (component) not to accomplish functions anticipated or affect system maintenance. This kind of error is general in the specific direct scenario and can be amended by a certain method.

It shows that the core elements of SREP are the *direct scenario*, *error* and *solution*.

The special property of the AE systems requirements knowledge ontology is its environment feature. Thus this paper merges the domain-related SREP [7] into the RKMOF. This paper uses programming in logic (Prolog) to represent the SREP because it not only expresses factual knowledge, but expresses rules.

Moreover, this paper constructs the RKMOF-based fact bank and transforms the instances represented in web ontology language (OWL) of the fact bank into the facts represented in Prolog grammar. The SREP needs to be brought into the rule bank. The rules in the rule bank are in Prolog grammar form, thus they do not need to be transformed. The concepts and predicates which these rules use should obey the definitions in the RKMOF to hold consistency with the concepts in the fact bank.

5 The RKMOF-based requirements elicitation approach with the SREP

In section 5, we present the procedure of the RKMOF-based requirements elicitation approach with the SREP which consists of the preparation stage and implementation stage.

A. In the preparation stage, the AEGO is constructed by domain experts and the domain SREP base is constructed by testers and domain experts.

The process of AEGO construction is,

1) Ascertaining the range and purpose of AEGO,

2) Eliciting the preliminary knowledge according to experts' options and stakeholders' requirements,

3) Obtaining the informal description of concepts, properties, class hierarchies and relations by data analysis,

4) Constructing the initial informal AEGO.

After the above steps, the knowledge structure of the AEGO can be obtained. This stage is basic because it supplies a knowledge treasure for the next stage.

B. The process of the implementation stage is below.

1) The TO is constructed by domain experts.

2) The DO is constructed by domain experts and requirements analysts. After this step, the knowledge structure of the DO in section 3 can be obtained.

3) The DRM can be constructed by requirements eliciting based on the TO and DO. This method is multi-view and guarantees the DRM to obey domain criterions.

4) Refinement of initial requirements can be implemented by detecting missing requirements items, adding the missing requirements items and striking out unrealistic functions and time expectations.

5) The AO can be constructed by eliciting and classifying of application domain concepts and relations. This process is user-oriented. UML class diagram can be adopted because the AO reflects the static knowledge of system.

6) The ARM can be constructed based on the DRM and AO. The ARM involves the dynamic knowledge of the application system. Therefore use cases should be developed by requirements analysts and domain users. The process of use case development is,

a) Determining the boundary of use case,

b) Identifying scenario, including the precondition, post condition and steps,

c) Identifying the primary and secondary scenarios,

d) Adopting UML use case diagram and activity diagram to represent use case.

Use case diagram reflects system functions observed by users. Therefore it is relatively stable. While activity diagram can be used to model work flow among different components, illustrate conditions of use case and system state. Therefore it is fluctuant. An instance of activity diagram is shown in Fig.4.

As shown in Fig.4, the alternative path is expressed by a rhombus. Therefore the diagram has parallel expression so that it can represent the same actions and control flow as in the RETO.

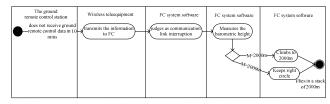


Fig. 4 An activity diagram of UAV FC system software

The RETO describes the aim, inference steps and control flow of the requirements elicitation. Therefore activity diagram should be transformed into the RETO. The RETO corresponding to Fig.4 is shown in Fig.5.

| Ontology name: requirement elicitation task ontology |
|---|
| Type: task-ontology |
| {ID: (omitted) |
| Requirement-Elicitation Task: = <task &&="" (uav="" (wireless<="" flying)="" id,="" in="" is="" of="" process="" th="" the=""></task> |
| teleequipment does not receive ground remote control data in 10 mins)> |
| Requirement-Elicitation Task-PSM: = < Competence, Operational specification, Requirements > |
| Competence: = < FC system software judges the system to be communication link interruption. |
| && (UAV outputs the height and attitude information in normal condition.) && (UAV obtains |
| the sequence of actions of FC system in corresponding condition.)> |
| Operational specification: = < Inference Steps and Control Flow between the Inference Steps: |
| |
| If (Wireless teleequipment does not receive ground remote control data in 10 mins to cause) |
| FC system software judges the system to be communication link interruption, |
| FC system software determines the state of UAV, |
| If (barometric height<2000m) |
| FC system software determines the height of climbing, |
| Else |
| FC system software determines to hold UAV flying in a stack && keep right circle, |
| Return this requirements item |
| } |
| Requirements: = < Concepts ∈ DomConcepts, Relations ∈ DomRelations, Rules ∈ Domrule > |
| Requirement-Elicitation Taskmap: {(Requirement-Elicitation Task Concepts = DomConcepts) -> |
| Concepts} |
| } - |
| |

Fig. 5 The UAV FC system software communication link interruption treating RETO

e) Considering abnormal scenario. This step includes the following sub-steps.

i The SREP should be mapped from the AEGO hierarchy to the DO hierarchy.

The SREP introduced in the section 4 is located in the AEGO hierarchy which is too abstract to apply. Therefore it is necessary to map it onto the DO hierarchy. The concrete process is based on the element *Dommap* in the DO definition. However the mapping is the inverse mapping of *Dommp*.

ii The SREP should be weaved into the RETO by AOM.

The RETO in the Fig.5 considers the normal conditions. However it does not consider the abnormal conditions and may neglect some important errors which may cause system to malfunction. Therefore the SREP should be weaved into the RETO to enrich the knowledge. Moreover, we find that some actions of system or environment always exist in more than one requirement items. We call this kind of action "crosscutting concerns". Fig.6 shows an instance of crosscutting concerns. In Fig.6, "Pre-flight switch instruction has been executed" cross cuts two safety

requirements items. Therefore it is a "crosscutting concerns".

AOM is useful in the security requirements elicitation [8]. We also consider this method to be useful in ontology-based requirements elicitation approach for weaving of the SREP.

| Requirements item 1: Parachuting Pre-flight switch instruction has been executed | Requirements item 2: Oil draining Pre-flight switch instruction has been executed |
|--|--|
| Requirements item 1: Parachuting Requirements item 2: Oil draining | Aspect: (The joinpoint is the time point before parachuting or oil draining) Pre-Jight switch instruction has been executed |

Fig. 6 An instance of crosscutting concerns

Activity diagram can model work flow for use case diagram in detail. Meanwhile, occurrence of activity, achievement of function and work flow in activity diagram emerge in certain scenario which is the same with the scenario of the SREP. Therefore this paper uses AOM to weave the SREP into the RETO, i.e., the corresponding event sequence of activity diagram, according to scenario occurrence place and condition by adopting SLAF [9].

The primary scenario expresses the normal actions of agent and environment. For instance, "UAV parachutes", the verb "parachutes" is analyzed as the data flow concept. As shown in Fig.5, the alternative path which is expressed by "if...else..." statement reflects the control flow as in programming languages.

The scenario fragment represents the secondary scenario expressing the abnormal actions of agent and environment. It derives from the SREP. The description template of a scenario fragment is shown below.

| 0 |
|---|
| [Name of a secondary scenario][object1, object2,] |
| Event[occurrence place] |
| Condition [occurrence condition] |
| { |
| |
| Sequence of events . |
| |
| } |

Fig. 7 The description template of a scenario fragment

In Fig.7, the scenario fragment corresponds to aspect, and the "event", "condition" and "sequence of events" are for "joinpoint", "pointcut" and "advice" in the aspectoriented technique. The "event" and "condition" determine the place where the scenario fragment is woven.

Fig.8 shows an instance of weaving scenario. The first part of the figure represents the primary scenario of UAV instruction panachuting which is normal. The second and the third parts give the secondary scenarios of the SREP1 and SREP2. In this approach, we adopts "if" and "while" directives for scenario fragment weaving. Therefore the form of weaved scenario is the same with the RETO and can be used as the result of requirements elicitation. In the process of weaving, we weave the scenario fragment into the place where the action may occur. The event statements that agree with the specific

verbs or nouns in the AO knowledge base are the joinpoints. Therefore the effectiveness of this method depends on the quality of the AO knowledge base greatly.

| | 0 | |
|--|--|-------------------------|
| Primary scenario of UAV instruction parachuting | | |
| [UAV parachutes in the remote status][FC system software, sensor] | | |
| { | | |
| UAV is in the process of airline flying | | |
| If (((inertial navigation equipment is fault)&&(GPS is fault)) ((air-data compute | er is fault)&&(radio | o altimeter is fault))) |
| Then FC system software computes angle-of-yaw | | |
| UAV returns to base UAV oil drains | | |
| | | |
| UAV instruction parachutes //Parachuting is in the remote status | | |
| Secondary scenario of SREP1 | | |
| [Oil draining][FC system software, oil sensor] | | |
| Event[FC system software gives the instruction of oil draining] | | |
| Condition[Pre-flight switch instruction is missing before the instruction of oil drain | vinal | |
| f | шы | |
| UAV oil drains without triggering the pre-flight switch instruction | | |
| } | | |
| | | |
| Secondary scenario of SREP2 | | |
| [Parachuting][FC system software, servo system] | | |
| | | |
| Event[FC system software gives the instruction of parachuting] | | |
| | ting] | |
| Event[FC system software gives the instruction of parachuting] Condition[Pre-flight switch instruction is missing before the instruction of parachu { | ting] | |
| Event[FC system software gives the instruction of parachuting] | ting] | |
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| Event[FC system software gives the instruction of parachuting] Condition[Pre-flight switch instruction is missing before the instruction of parachut { UAV parachutes without triggering the pre-flight switch instruction } The results of weaving the two secondary scenarios into the primary scenario [UAV parachutes in the remote status][FC system software, sensor, servo system] { UAV is in the process of airline flying If ((inertial anvigation equipment is fault)g&&(GPS is fault))]!((air-data compute Then FC system software computes angle-oFyaw UAV returns to base FC system software gives the instruction of old fraining if pre-flight switch instruction is missing before oil draining if pre-flight switch instruction is missing before oil draining FC system software gives the instruction UAV oil drains FC system software gives the instruction UAV aid regions the pre-flight switch instruc- flight switch instruction is missing before parachuting if pre-flight switch instruction is missing before parachuting infight switch instruc- parachuting, trigger the pre-flight switch instruc- | er is fault)&&(radia n software gives the on and oil drains m software gives th | instruction of oil |

Fig. 8 An instance of weaving scenario

6 Case studies

This paper constructs ontology of a subsystem of UAV FC system including several continuous versions of a certain type of UAV FC systems software. Moreover, we adopt the comparison experiment to inspect the RSs to validate the effectiveness of the proposed approach. The comparative method [2] is used for version 3.3.x and the proposed method is used for version 3.3.(x+1).

Tab. 4 The SREP manifestation and severity level distribution of a certain type of UAV FC system software

| | Error number of each significance degree+ | | | | | | | |
|--------------------------------|---|------------|------------------|-----------|------------|------------|------------|-------------|
| Manifestatione | /Total number of errors¢ ³ | | | | | | | |
| Manifestation | Set I 🕫 | | | Set II +2 | | | | |
| | C⇔ | I¢ | 0 | T₽ | C₽ | I₽ | 0 0 | T⇔T |
| Function € | 0 € | 1₽ | 10 | 2₽ | 0 ₽ | 0 ₽ | 2₽ | 2¢2 |
| Performance∉ | 0 ¢∂ | 1 ₽ | 0 ₽ | 10 | 0 ₽ | 10 | 0 ₽ | 10 |
| Interface₽ | 0 ¢ | 2₽ | 3₽ | 5₽ | 0 ₽ | 1₽ | 3₽ | 4⇔ |
| Safety₽ | 1₽ | 1₽ | <mark>0</mark> ₽ | 2₽ | 1₽ | 0 ₽ | 0 ₽ | 10 |
| Environment₽ | 1₽ | 2₽ | 0 ₽ | 3₽ | 0 ₽ | 0 ₽ | 0 0 | 0 ¢2 |
| Maintenance₽ | 0 ¢ | 1₽ | 10 | 2₽ | 0₽ | 0 ₽ | 2₽ | 2₽ |
| D ocument+ ² | 0 ¢ | 1₽ | 3₽ | 4₽ | 0₽ | 2₽ | 2₽ | 4€ |
| Total₽ | 19÷ | | | | 1 | 4₽ | | |

Note: C, I and O stand for severity level "critical", "important" and "ordinary". T stands for "total".

Tab.4 records the results of the RS inspection. The set I adopts the comparative method and the set II adopts ontology-based method introduced in this paper.

It shows that the total number of errors of the set I is larger than the set II. The number and severity level distribution of performance errors in the set I is the same with the set II. The number of function errors of the set I is the same with the set II; however, the severity level distributions of them are different. The results of maintenance error and document error are the same with the function error. The number of the rest kinds of errors in the set I is larger than the set II respective with the set I having more severe errors. Moreover the number of environment errors in the set II is zero.

This paper adopts metrics [1] to estimate the RS quality quantitatively. Note that |Con|=36 and |Rel|=45. |ReqItem| of RS 1 is 11 while |ReqItem| of RS 2 is 13. Tab.5 gives the quality measure results of RS 1 and RS 2. Tab. 5 Quality measure results of RS 1 and 2

| ıb. : | 5 Quality i | alts of KS 1 | anc | |
|-------|-------------|--------------|------|--|
| | Metrics∉ | RS1₽ | RS2≁ | |

| Metrics⇔ | KSI₽ | K52+ |
|---------------|-------------------------|---------------|
| Correctness₽ | 9/11=81.8%+7 | 13/13=100%+2 |
| Completeness# | 68/81=84%+ ³ | 77/81=95%+3 |
| Consistency¢ | 14/23=60.9% | 15/23=65.2%+2 |
| | 1.00 | C ((|

There is an evident difference of "correctness" and "completeness" between the RS 1 and 2. For "correctness", ideally, all requirements items should be mapped onto ontology because ontology is the semantic basis of problem domain. Therefore, "correctness" can reflect the ratio of mapping elements. The higher ratio is the better quality RS possesses. The result shows that some requirements items of the RS 1 do not correspond to the ontology knowledge base. For "completeness", ideally, all ontology elements should be referred in RS. Therefore, "completeness" can reflect the ratio of mapping elements. The higher ratio is the better quality RS possesses. The result shows that the knowledge which the RS 1 involves is incomplete because many ontology elements have not emerged in the RS 1. That is because the requirements elicitation of RS 1 is only based on the multi-ontology framework which does not involve the SREP. The experiment results also show that the completeness of knowledge in requirements knowledge ontology will affect the requirements development greatly.

The results also show that "consistency" of two RSs is low. It explains the cause of the relatively large number of interface errors in Tab.4. Therefore the ontology should be complemented by adding the interface knowledge.

The deficiency of this experiment is that it analyzes the quality of RS only by its static property. Thus, how to estimate the quality of RS by the dynamic property directly needs to be further studied.

7 Conclusions

We propose a RKMOF-based requirements elicitation approach with the SREP for AE system software. Firstly, we construct the AE systems RKMOF. Secondly, we present the construction elements of AE systems requirements knowledge ontology. Thirdly, we adopt the AEGO, DO, TO and AO to express knowledge in different hierarchies. Details are also given. Furthermore, the definition and representation of SREP are presented. Finally, the detailed processes of RKMOFbased requirements elicitation approach with the SREP are given. The experiment results validate the effectiveness of the proposed approach preliminarily. However, our studies still have some deficiencies. Thus, the following issues will be further discussed, 1) The SREP bank should be enriched to involve more SREP to play a role of error-prevention in requirements elicitation; 2) How to estimate the quality of RS by the dynamic property directly needs to be further studied: 3) Results of the experiment show that the number of interface errors of the set II is not small. It means that the knowledge of interface is relatively incomplete. Therefore, the interface property should be further described.

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